

**HRI 2019 Best Award****[DEMO]**

<b>Best Demo</b>	<b>Demo: Pointing Gestures for Proximity Interaction</b> Boris Gromov (Dalle Molle Institute for Artificial Intelligence (IDSIA, SUPSI/USI)), Jérôme Guzzi (IDSIA), Luca Gambardella, Alessandro Giusti (Dalle Molle Institute for Artificial Intelligence (IDSIA, SUPSI/USI))
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**[Late Breaking Report]**

<b>3<sup>rd</sup> Prize</b>	<b>Affective Robot Movement Generation Using CycleGANs</b> Michael Suguitan (Cornell University), Mason Bretan (Samsung Research America), Guy Hoffman (Cornell University)
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<b>3<sup>rd</sup> Prize</b>	<b>Multi-axial Soft Stretch Sensor Based on Anisotropic Electrical Impedance Tomography</b> Hyunkyu Park (Korea Advanced Institute of Science and Technology), Kyungseo Park (Korea Advanced Institute of Science and Technology), Wondong Kim (Korea Advanced Institute of Science and Technology), Jung Kim (Korea Advanced Institute of Science and Technology)
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<b>2<sup>nd</sup> Prize</b>	<b>Humanoid Therapy Robot for Encouraging Exercise in Dementia Patients</b> Mariah Schrum (Georgia Institute of Technology), Chung Hyuk Park (George Washington University), Ayanna Howard (Georgia Institute of Technology)
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<b>1<sup>st</sup> Prize</b>	<b>A Social Robot for Autonomous Health Data Acquisition among Hospitalized Patients: An Exploratory Field Study</b> Daisy van der Putte (Erasmus University), Roel Boumans (Radboud University Medical Center & Delft University of Technology), Mark Neerinx (Delft University of Technology), Marcel Olde Rikkert (Radboud University Medical Center), Marleen de Mul (Erasmus University)
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**[VIDEO]**

<b>Reviewers' Choice</b>	<b>Video: Pointing Gestures for Proximity Interaction</b> Boris Gromov (Dalle Molle Institute for Artificial Intelligence (IDSIA, SUPSI/USI)), Jérôme Guzzi (IDSIA), Luca Gambardella, Alessandro Giusti (Dalle Molle Institute for Artificial Intelligence (IDSIA, SUPSI/USI))
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<b>People's Choice</b>	<b>Exploring Collaborative Interactions Between Robots and Blind People</b> Filipa Correia (INESC-ID & Instituto Superior Técnico, Universidade de Lisboa), Raquel Oliveira (Instituto Universitário de Lisboa (ISCTE-IUL, CIS-IUL)), Mayara Bonani (Universidade de São Paulo), André Rodrigues (Universidade de Lisboa), Tiago Guerreiro (University of Lisbon), Ana Paiva (INESC-ID)
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<b>Best Video</b>	<b>How Can You Touch and Feel via Telerobots?</b> Yunjoo Kim, Junghoon Park, Seungryul Kim, Jung Kim (Korea Advanced Institute of Science and Technology), Jeonghye Han (Cheongju National University of Education)
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**[Student Design Competition]**

<b>Delegates' Choice</b>	<b>Pomelo, a Collaborative Education Technology Interaction Robot</b> Liora Nasi, Yoel Yusuf Nasi, Can Aydin, Rana Taki, Batuhan Bayraktar, Ece Tabag, Sedat Yalcin (Hisar School)
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<b>2<sup>nd</sup> Prize</b>	<b>AVEC*: Power Assist Vehicle Enriching Communication using Intuitive Interface</b> Jaehoon Kim (Seoul National University), Minkyung Kim (Korea Advanced Institute of Science and Technology), Hotae Lee, Keunwook Kim, Jungwook Moon (Seoul National University)
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<b>1<sup>st</sup> Prize</b>	<b>Lumigami</b> Alexa Marz, Constantino Brito, Regina Vargas (Centro de Diseño, Cine y Television)
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<b>[Full Paper]</b>	
<b>HRI Design</b>	<b>Using Skin Texture Change to Design Emotion Expression in Social Robots</b> Yuhan Hu (Cornell University), Guy Hoffman (Cornell University)
<b>Theory and Methods in HRI</b>	<b>Children's Responding to Humanlike Robots Reflects an Uncanny Valley</b> Megan Strait (The University of Texas Rio Grande Valley), Heather L. Urry (Tufts University), Paul Muentener (Tufts University)
<b>HRI User Studies</b>	<b>Second Language Tutoring using Social Robots: A Large-Scale Study</b> Paul Vogt, Rianne van den Berghe, Mirjam de Haas, Laura Hoffmann, Junko Kanero, Ezgi Mamus, Jean-Marc Montanier, Cansu Oranç, Ora Oudgenoeg- Paz, Daniel Hernández García, Fotios Papadopoulos, Thorsten Schodde, Josje Verhagen, Christopher D. Wallbridge, Bram Willemsen, Jan de Wit, Tony Belpaeme, Tilbe Göksun, Stefan Kopp, Emiel Krahmer , Aylin C. Küntay, Paul Leseman, Amit Kumar Pandey
<b>Technical Advanced in HRI</b>	<b>Transfer depends on Acquisition: Analyzing Manipulation Strategies for Robotic Feeding</b> Daniel Gallenberger, Tapomayukh Bhattacharjee, Youngsun Kim and Siddhartha S. Srinivasa (University of Washington)