



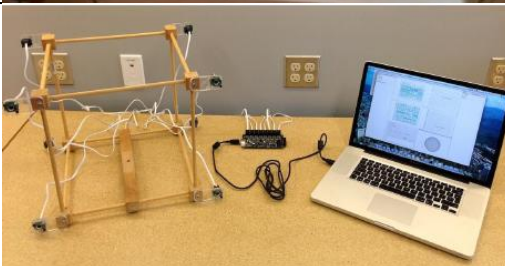

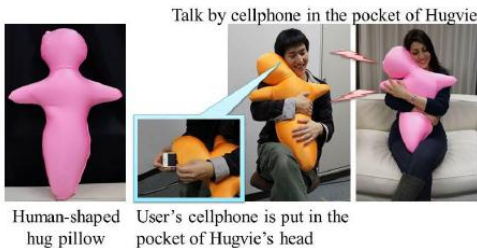
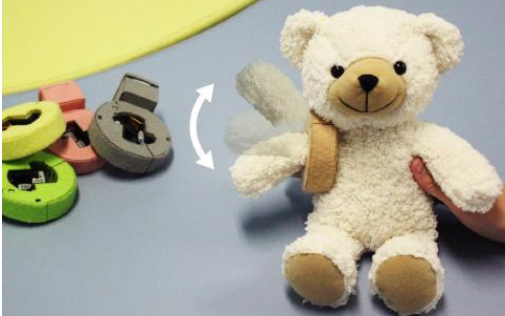




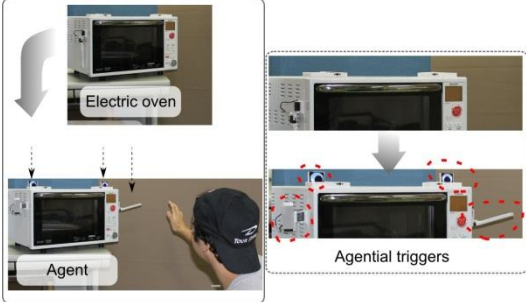




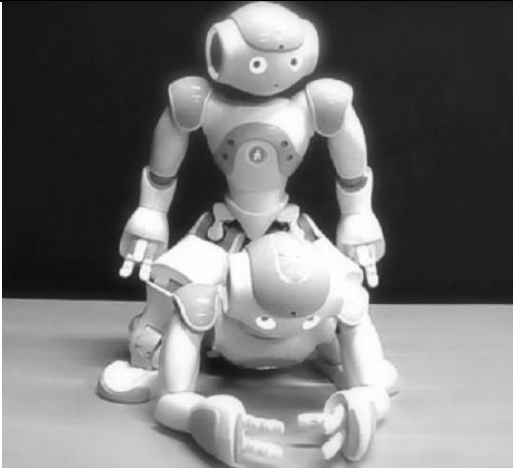

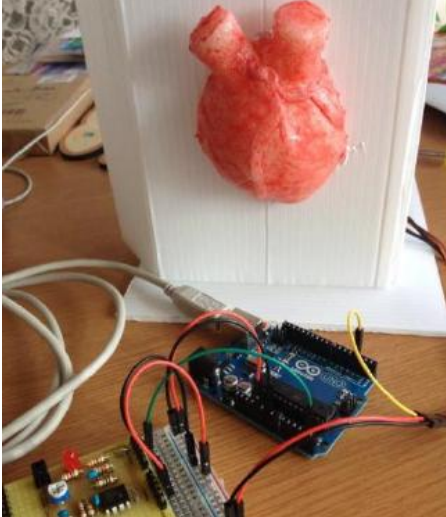



<p>D1</p>	<p>Robotic Wheelchair Moving Alongside a Companion</p>	<p>Ryota Suzuki, Yoshihisa Sato, Yoshinori Kobayashi, Yoshinori Kuno, Keiichi Yamazaki (Saitama University), Masaya Arai, Akiko Yamazaki (Tokyo University of Technology)</p>	
<p>D2</p>	<p>Strengthening Social Telepresence and Social Bonding by a Remote Handshake</p>	<p>Yuya Wada, Kazuaki Tanaka, Hideyuki Nakanishi (Osaka University)</p>	
<p>D3</p>	<p>TEROOS: A Wearable Avatar to Enhance Joint Activities</p>	<p>Tadakazu Kashiwabara, Tatsuki Ohnishi, Hiroataka Osawa (Keio University), Kazuhiko Shinozawa (ATR), Michita Imai (Keio University)</p>	
<p>D4</p>	<p>Why do the people interact with the shadow circles?</p>	<p>Takafumi Sakamoto, Yugo Takeuchi (Shizuoka University)</p>	
<p>D5</p>	<p>An Open Hardware and Software Microphone Array System for Robotic Applications</p>	<p>François Grondin, Dominic Létourneau, François Ferland, François Michaud (Université de Sherbrooke)</p>	

<p>D6</p>	<p>The Design of Social Robot</p>	<p>Seita Koike (Tokyo City University)</p>	
<p>D7</p>	<p>Evoking an Affection for Communication Partner by a Robotic Communication Medium</p>	<p>Takashi Minato, Shuichi Nishio (ATR), Hiroshi Ishiguro (Osaka University)</p>	 <p>Talk by cellphone in the pocket of Hugvie</p> <p>Human-shaped hug pillow</p> <p>User's cellphone is put in the pocket of Hugvie's head</p>
<p>D8</p>	<p>PINOKY: A Ring That Animates Your Plush Toys</p>	<p>Yuta Sugiura, Yasutoshi Makino (Keio University), Daisuke Sakamoto (The University of Tokyo), Masahiko Inami (Keio University), Takeo Igarashi (The University of Tokyo)</p>	
<p>D9</p>	<p>A Surrogate Robot with Deictic Pointing Capability</p>	<p>Hiroaki Kawanobe, Yoshifumi Aosaki, Hideaki Kuzuoka (University of Tsukuba), Yusuke Suzuki (Oki Electric Industry Co., Ltd.)</p>	
<p>D10</p>	<p>Interaction with Blended Reality Agent "BReA"</p>	<p>Yusuke Kanai, Hirotaka Osawa, Michita Imai (Keio University)</p>	 <p>Continuously transference</p> <p>Interaction with on-screen agent</p> <p>Interaction with robot agent</p>

<p>D11</p>	<p>Sociable Creatures for Child-Robot Interaction Studies</p>	<p>Yasutaka Takeda, Shohei Sawada, Tatsuya Mori, Kohei Yoshida, Yu Arita, Takahiro Asano, Naoki Ohshima, Ravindra De Silva, Michio Okada (Toyohashi University of Technology)</p>	
<p>D12</p>	<p>Physiotherapy demonstration with NAO</p>	<p>David López Recio, Elena Márquez Segura (Mobile Life), Luis Márquez Segura (Fonserrana S.C.A de interés social), Annika Waern (Mobile Life)</p>	
<p>D13</p>	<p>Human-Agent Interaction by Transformative Agential Triggers</p>	<p>Hiroataka Osawa, Michita Imai (Keio University)</p>	
<p>D14</p>	<p>Superimposed Self-Character Mediated Video Chat System for Face-to-Face Interaction Based on the Detection of Talkers' Face Angles</p>	<p>Tomohiro Takada, Shiho Nakayama, Yutaka Ishii, Tomio Watanabe (Okayama Prefectural University)</p>	
<p>D15</p>	<p>Shape Shifting Information Notification based on Peripheral Cognition Technology</p>	<p>Kazuki Kobayashi (Shinshu University), Seiji Yamada (National Institute of Informatics)</p>	

<p>D16</p>	<p>Perceiving the Active Chair: Agent or Machine?</p>	<p>Peng Li, Kazunori Terada, Akira Ito (Gifu University)</p>	
<p>D17</p>	<p>Building Table-Talk Agents that Create a Pleasant Atmosphere</p>	<p>Masahide Yuasa (Tokyo Denki Univ.)</p>	
<p>D18</p>	<p>Robot Gangnam Style!</p>	<p>Eduardo Sandoval, Christoph Bartneck (University of Canterbury)</p>	
<p>D19</p>	<p>Attitude-aware communication behaviors of a partner robot: politeness for the master</p>	<p>Tomoko Yonezawa (Kansai University), Hirotake Yamazoe (Osaka University), Yuichi Koyama (Nagoya University), Naoto Yoshida (Kansai University), Shinji Abe (Hiroshima Institute of Technology), Kenji Mase (Nagoya University)</p>	

<p>D20</p>	<p>Ikitomical Model: extended body sensation through a cardiovascular robot</p>	<p>Yuka Nagata, Yuka Niimoto, Naoto Yoshida, Tomoko Yonezawa (Kansai University)</p>	
<p>D21</p>	<p>Exploring Anti-social Behavior as a Method to Understand Aspect of Social Behavior</p>	<p>Takao Watanabe, Masakatsu Fujie (Waseda University), Angelika Mader, Edwin Dertien (University of Twente)</p>	
<p>D22</p>	<p>Natural 3D Controls for Space Robotic Systems</p>	<p>Garrett Johnson, Victor Luo, Alex Menzies, David Mittman, Jeffrey Norris, Scott Davidoff (California Institute of Technology)</p>	